

University of Natural Resources and Life Sciences Vienna Department of Sustainable Agricultural Systems

Institute of Agricultural Engineering

Operational Sensors in Agriculture

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- 1. Precision farming
- 2. Sensor systems for precision crop farming
- 3. Challenges for the future development

1. Sectors of precision farming



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1. A short sidestep: precision live stock farming



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1. precision crop farming the vision of the early 90ies

(Auernhammer and Schueller 1991)



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currently 4 technologies for satelite navigation :

- autonomous (GPS, GLONASS, BeiDou, GALLILEO),
- wide area differential GPS (WADGPS),
- precise point positioning DGPS (PPP DGPS),
- real time kinematic (RTK)

Positioning accuracy

(Circular Error Probability, CEP): autonomous: <10m WA DGPS: 0.5-2m PPP DGPS: 0.04-0.5m RTK: 0.015 - 0.05 m



Hayes, 2012, European Commission,; IGS-workshop, Olztyn, Poland

2. Sensors for precision crop farming: Reduced overlap by automatic steering system and RTK-georeferred seeder



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reduction of resource input (seeds, fuel, fertilizer, pesticides, working time) about 15%



2. Sensors for precision crop farming Mapping or online N sensoring for the fertilizer broadcasting



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Increase of

yealds %

1-2



2. Sensors for precision crop farming <u>Map information</u>



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2. Sensors for precision crop farming Traditional field scouting



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2. Sensors for precision crop farming (Available soil sensors



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2. Sensors for precision crop farming Soil information: EM-measurement



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2. Sensors for precision crop farming Soil information: EM-measurement



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Source: Geoprospectors



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Source: Geoprospectors

2. Sensors for precision crop farming: (III) Soil information TSM



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2. Sensors for precision crop farming: Automatic monitoring of quality



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2. Sensors for precision crop farming:Automatic monitoring of yields andyield qualities



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2. Sensors for precision crop farming: **University of Natural Resources** and Life Sciences Vienna Department of Sustainable implementation into harvester Agricultural Systems Institute of Agricultural Engineering Parameter TM Roh-Roh-Roh-Roh-Methan-NEL ME gas¹⁾ prot. faser asche fett % % FM % FM % FM MJ FM MJ FM % FM nl/kg 102 102 103 102 102 103 103 103 Probenzahl MIN Wert 2.3 5.1 1.1 1.3 2,2 23.3 0,460.1MAX-Wert 2.3 45.2 4.3 12.1 1,0 112,9 2,4 4,1 Mittelwert 36,4 3,0 9.1 1.6 0,7 93.1 2.03,4 0.939 0.980 0.983 0.990 0.907 0,789 0.837 0.984 NIRS Ο

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2. Sensors for precision crop farming: Effects of site specific fertilization on yield and protein content in durum wheat



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Figure 2. Maps of wheat yield (left) and grain protein (right), divided in the different management zones: HFZ (130+0 N, 130+15 N), MFZ (160+0 N, 160+15 N), LFM (200+0 N, 200+15 N).

Source: Morari, F. et al. 2013: Precision agriculture '13



Figure 4. Maps of apparent N balance (left) and N use efficiency (%) (right).

Challenges: Data processing (amount + real time)



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What we want

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What we get



We drown in a sea of data and thirst for information

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3. Challenges: the vision of the early 90ies

(Auernhammer and Schueller 1991)



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3. Challenges: Sensor fusion and data processing



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REDIT

I can do everything

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manufacture independent open interfaces

 communication between human-machine, machine-tools and machine-machine

sensor and information fusion opens:

- automation of processes and data documentation
- Serverarchitecture (internal external cloud)
- data warehouse for expert systems and administrative tools
- "open link" for ICT in agri- and horticulture
- development of new "Apps" open immense possibilities for users

Cell phone = Swiss army knife

3. Challenges: Open interfaces for ICT



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- Doubling of processor speed every 18 month
- Doubeling of transfer speed every 9 month
- Number of mobile telefones increased from 750 Mio. (2000) to 6 Mrd. (now)



3. Challenges: Open data link for ICT



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3. Challenges: Open data link for ICT



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